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Call for Papers

Topical Collection on Nonlinear Dynamics of Small-Scale Robotics

This collection aims to explore advancements and applications of small-scale robots, with emphasis on their complex dynamic behaviors and control solutions. Original papers and reviews are welcome on **theoretical, computational, and experimental aspects of small-scale robotics**, including but not limited to mathematical modelling, dynamic analysis, control design and optimization, and experimental validation.

Editors:

Yang Liu University of Exeter, Exeter, UK

Hector Gutierrez Florida Institute of Technology, FL, USA

Submission:

Instructions for submission and further information can be found on the journal website. When submitting your paper, select “Nonlinear dynamics of small-scale robotics” from the pull-down menu. All submitted papers will undergo rigorous peer review upon receipt. Accepted papers will be immediately available online in the "Online First" section.

Key Dates:

1st June 2024 Open for submission

1st June 2025 Submission deadline

For any questions, please do not hesitate to contact Professor Yang Liu (y.liu2@exeter.ac.uk) or Professor Hector Gutierrez (hgutier@fit.edu)